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Stabilization of Linear Systems

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This volume presents full survey of stabilization theory for linear control systems. The flow of publications concerned with the methods of stabilization for linear control systems increases in the last 30 years. The book sets out these new methods for solution of the problem of stabilization and pole assigned. The methods of low-frequency stabilization and high-frequency stabilization for solution of the Brockett problem are presented.

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- Poincare mapping, realizing the embedding of unstable manifolds, are constructed.

The **Stabilization of Linear Systems** addressed to specialists in dynamical systems, applied differential equations, and the control theory. It may be useful for graduated students in mathematics, control theory, and mechanical engineering.

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